Product Recommendation Information Sheet

			Roll F	eed			
Desired Proc	duct If you have no	desired product	t, leave the applicable fields I	olank. We will call	you if necessary.		
Desired Motor(s)			,				
	X <i>step</i> Stepper Moto		or 🗌 Servo M		otor 🗌 Brushless Moto		
□ AC Motor	□Others						
Desired Controller							
Oriental Motor co	ontroller Ouse progr	ositioning ammable	function of anothe controller, etc.	r company's	s PLC, O Unknov	vn	
If you wish to use a	product from anoth					me.	
Manufacturer nam	ne:	-	Product nar	ne:			
	nism Specifi	[e applicable fields	s blank. We will call you if nece	ssary.	Mote
-	eter ·····	$D_{P1} =$	mm	Í			Primary Side Pulle
	h (Thickness)······· erial ·····	$L_{P1} =$ Materials:	mm] 1	Secondary Side Pulley		
•	S	$m_{P1} =$	kg/unit	ĺ			Drive Roll
_	Rollers	$n_{P1} =$	unit(s)	1	Load		
-	neter ·····	$D_{P2} =$	mm	1	Load		Driven Roll
Driven Roller Wic	th (Thickness)······	L _{P2} =		j			
Driven Roller Mat	terial	Materials:		1			
Driven Roller Mas	SS	<i>m</i> _{P2} =	kg/unit	j	~		
Number of Driver	n Rollers	<i>п</i> _{Р2} =	unit(s)]		, A	
Rolling Friction C	oefficient	μ =]	¹	Position	of Mechanism
Roll Pressure ·····		Fo =	Ν]			
Total Mass of Loa	ad	<i>m</i> =	kg]			
Inclination Angle	of the Mechanism $\cdot\cdot$	$\theta =$	deg.]			
Tension (External	force)	<i>F</i> _A =	N]			
If you are pulling out ar Maximum Diame	ter of Roll	on a roll, s $D_1 =$	uch as tape, fill in th mm	າe following]			
Roll Mass		<i>m</i> ¹ =	kg]			
Please enter if you use	connecting belt pull	ey or gear.	Not required for dir	ect connect	tion.		
Primary Side Pulley I	Diameter and Mass	D _{P1} =	mm	<i>m</i> _{P1} =	kg]	
If the mass i	s unknown, please e	nter the w	idth and material	→ L _{P1} =	mm	Materials:	
Secondary Side Pulle	ey Diameter and Mass…	D _{P2} =	mm	<i>m</i> _{P2} =	kg]	
If the mass i	s unknown, please e	nter the w	idth and material	→ <i>L</i> _{P2} =	mm	Materials:	
Operating C		n doubt, leave t	he applicable fields blank. W				
	er Operation		mm	Travel	I Speed V		
			S	ļ	Travel A	mount [mm]	
-	and Deceleration Time.	$t_1 =$	S	ļ			
		$t_2 =$	S	ļ		Deceleration	
	beed (If any)	V =	mm/s] ī	Positionir	Time to [S]	Stop Time t2 [S]
	g Accuracy (If any)		mm	<u> </u>			
	ltage ·····		V,	Hz			
Necessity of Holding	Force After Power is Tur	ned off	· O Yes	\bigcirc No			

Others

Application, Equipment Name		
Estimated Number of Units to be Used ·····		unit(s)
Estimated Purchase Date ·····	year	month
Supply Source (Sales office)		

Other (Requests, Contact information, Items not written above, etc.)