Product Recommendation Information Sheet

		Can	1		
■ Desired Product ● If you have	no desired product le	ave the annlicable fields bla	ank We will call you	ı if necessarv	
Desired Motor(s)	no desired product, ie	ave the applicable lielus bio	ank. We will can you	i i iiccessaiy.	
□ X STEP □ Stepper Motor		☐ Servo Motor		☐ Brushless Motor	
☐ AC Motor ☐ Others ☐					
Desired Controller					
Oriental Motor controller Us	e positioning for ogrammable co	unction of another ontroller, etc.	company's F	PLC, O Unknov	vn
If you wish to use a product from and	ther company,	enter the manufac	turer name a	nd the product nar	ne.
Manufacturer name:		Product nam	e:	,	
■ Drive Mechanism Speci ■ Total Mass of Load (Including table) ■ Guide Friction Coefficient		m ₁ =	applicable fields bla	ank. We will call you if nece:	ssary.
					Load
Cam Dimensions Diameter		Φ <i>Dc</i> =	mm		Table
Eccentricity Volume ······		'	mm	Guide	
Mass			kg		
Thickness (Only if mass is unknown)		t =	mm	Cam Follower (Cont	act area) Primary Side Pulley
Material (Only if mass is unknown)		Materials:			
Rolling Friction Coefficient of Cam Follower (Contact area) ···		$\mu =$		Disk Cam	Motor
Pushing Force (Not including the mass of the load)		F =	N	Secondary Side Pull	ey
Position of Mechanism ·····		○ Horizontal	O Vertical		Pushing Force F
Cam Wire Figure (If there is more than 1 s Travel Amount Cam Rotation Angle Please enter if you use connecting belt p			mm	Center of Rotation	Horizontal operation=0°
Primary Side Pulley Diameter and Mass ···	···· D _{P1} =	mm	<i>m</i> _{P1} =	kg	
If the mass is unknown, pleas		th and material. →	L _{P1} =	mm	Materials:
Secondary Side Pulley Diameter and Mass		mm	<i>m</i> _{P2} =	kg	
If the mass is unknown, pleas		th and material. →	L _{P2} =	mm	Materials:
For electric linear slide sizing, use the speci		applicable fields blank. We			
Continuous Operation Speed	N =	to ot	Rotation Sp /min	Jood IV	
Operating Time·····		s	7111111	/	am n Angle[*]
(The above speed should be entered as the rotation					
Operating in Positioning Operation				Acceleration Time ti	Deceleration Time t1
Cam Rotation Angle		۰		Positionin	g Time to [s] Stopping Time t2 [s]
Positioning Time	··· to =	S			
Acceleration/Deceleration Time ·····	··· [t ₁ =	S			
● Stop Time·····	··· [t ₂ =	S			
Desired Stopping Accuracy (If any)	±	۰			
Power Supply Voltage ·····		V,	Hz		
Necessity of Holding Force After Power is	Turned off ······	○ Yes	⊃ No		

Others			
pplication, Equipment Name			
timated Number of Units to be Used ·····		unit(s)	
timated Purchase Date	year	month	
ipply Source (Sales office)			
her (Requests, Contact information, Items not writ	tten above, etc.)		