Product Recommendation Information Sheet

Screw Linear Slide							
■ Desired Product ● If you have no	desired product, leave t	the applicable fields bla	ank. We will call you	if necessary.			
Desired Motor(s)							
☐ Q STEP ☐ Stepper Mot	or	☐ Servo Mo	otor	☐ Brushless Motor			
☐ AC Motor ☐ Others							
Desired Controller							
	positionina func	tion of another	companv's P	LC,			
Oriental Motor controller prog	positioning func grammable contr	oller, etc.	p y = .	Unknown			
If you wish to use a product from anoth	ner company, ent			nd the product name.			
Manufacturer name:		Product nam	e:				
☐ Screw Type ○ Precision ball screw ○ Rolle	ed ball screw	○ Trapezo	oidal screw/lea	ad screw			
■Drive Mechanism Specif	ications •	If in doubt, leave the	applicable fields bla	nk. We will call you if necessary.			
● Total Mass of Load (Including table)·	m =	kg			Loa		
Guide Friction Coefficient	·			Table	Guid		
Shaft Diameter of Ball Screw	D _B =	mm			Scre		
Overall Length of Ball Screw	<i>L</i> _B =	mm		Secondary Side Pulley	Connecting Bo		
● Ball Screw Lead ······	P _B =	mm/rev			Primary Side Pulle		
■ Ball Screw Efficiency ····································	$\eta_B =$			Motor			
Ball Screw Material	Materials:	:					
Preload	Fo =	N		~			
Inclination Angle of the Mechanism ·	θ =	deg.		(,,;	θ.		
External Force Applied (External force)	$F_A =$	N			Position of Mechanis		
Please enter if you use connecting belt pul	ley or gear. Not r	required for dire	ct connection	n			
Primary Side Pulley Diameter and Mass	$D_{P1} =$	mm	<i>m</i> _{P1} =	kg			
If the mass is unknown, please	enter the width a	and material. →	L _{P1} =	mm M	aterials:		
Secondary Side Pulley Diameter and Mass…		mm	<i>m</i> _{P2} =	kg			
If the mass is unknown, please		and material. →	$L_{P2} =$	mm M	aterials:		
For electric linear slide sizing, use the specific	request form.						
■Operating Conditions ● #	in doubt, leave the appli	icable fields blank. We	will call you if neces	ssary.			
● Travel Amount per Operation ····································		mm	Travel Sp	eed V			
Positioning Time	to =	S		Travel Amount	[mm]		
Desired Acceleration and Deceleration Time	t ₁ =	S		/ Inaver Amount			
● Stop Time ·····	t ₂ =	S		Acceleration Decele	ration		
Desired Travel Speed (If any)	V =	mm/s		Time tı T	ime tri		
■ Desired Stopping Accuracy (If any) ···	. ±	mm		Positioning Time	s to [S] Stop Time t2 [S]		
Power Supply Voltage		V,	Hz				
■ Necessity of Holding Force After Power is Tu	rned off	○ Yes (⊃ No				

Others			
pplication, Equipment Name			
timated Number of Units to be Used ·····		unit(s)	
timated Purchase Date	year	month	
ipply Source (Sales office)			
her (Requests, Contact information, Items not writ	tten above, etc.)		