Product Recommendation Information Sheet

Belt Conveyor									
Desired Product ● If you have no desired product, leave the applicable fields blank. We will call you if necessary.									
Desired Motor(s)									
□ <i>X</i> STEP □ Stepper Moto	r	☐ Servo Motor	r	☐ Brushless Moto	r				
☐ AC Motor ☐ Others									
——————————————————————————————————————									
Oriental Motor controller Use progr	ositioning for	unction of another ontroller, etc.	company's	PLC, O Unknow	vn				
If you wish to use a product from another	er company,	enter the manufac	turer name	and the product nar	me.				
Manufacturer name:		Product nam	ne:						
Conveyor Type									
○ Belt pulley ○ Chain sprod	ket								
Drive Mechanism Specific	cations	If in doubt, leave the	applicable fields	blank. We will call you if nece	ssary.				
● Total Mass of Load (Including table)··	m =	kg		Load					
Belt Mass	<i>т</i> в =	kg		Guide	Drive Pulle				
Friction Coefficient Between Belt and Guide -	μ =			Belt					
Number of Drive Pulleys	n =	unit(s)		Dell	Primary Side Pulle				
Pitch Circle Diameter of the Drive Pulley	D _P =	mm		Drive Pulley	Mate				
Drive Pulley Inner Diameter	D _{Pi} =	mm		Secondary Side Pu	lley Moto				
Drive Pulley Width (Thickness)	L _P =	mm			,				
Drive Pulley Mass	m _P =	kg/unit							
Drive Pulley Material	Materials:	1.9,							
● Inclination Angle of the Mechanism ··	$\theta =$	deg.		θ	Desition of Machanian				
External Force Applied (External force)	$F_A =$	N			Position of Mechanism				
Please enter if you use connecting belt pulle		lot required for dire	ect connecti	on.	1				
Primary Side Pulley Diameter and Mass		mm	<i>m</i> _{P1} =	kg					
If the mass is unknown, please e	nter the wid	th and material. →	L _{P1} =	mm	Materials:				
Secondary Side Pulley Diameter and Mass…	D _{P2} =	mm	<i>m</i> _{P2} =	kg					
If the mass is unknown, please e	nter the wid	th and material. →	$L_{P2} =$	mm	Materials:				
For electric linear slide sizing, use the specific r	equest form.								
■Operating Conditions ● ##	doubt, leave the	applicable fields blank. We	will call you if ne	cessary.					
Travel Amount per Operation		mm		Speed V					
Positioning Time Position Application and Possilaration Time	to =	S		Travel A	mount [mm]				
Desired Acceleration and Deceleration Time	t ₁ =	S							
Stop Time	$t_2 =$	S		Acceleration Time t1	Deceleration Time t1				
Desired Travel Speed (If any)	V =	mm/s			g Time t0 [s] Stopping Time t2 [s]				
Desired Stopping Accuracy (If any)…	土	mm			2 (-) +				
Power Supply Voltage		V,	Hz						
Necessity of Holding Force After Power is Turn	ed off ·····	○ Yes	○ No						

Others			
Application, Equipment Name·····			
Estimated Number of Units to be Used ·····		unit(s)	
Estimated Purchase Date	year	month	
Supply Source (Sales office)			
Other (Requests, Contact information, Items not wri	itten above, etc.)		