## **Product Recommendation Information Sheet**

## **Opening and Shutting Doors**

Desired Motor(s)    Caster   Stepper Motor   Servo Motor   Electric Actuator   Brushless Motor	Desired P	roduct If you have no desir	ed product, leave the applicable fields	blank. We will call you if necessary.	
Desired Controller  Oriental Motor controller Oriental Specifications Oriental Motor controller					
Desired Controller  Oriental Motor controller  Programmable controller, etc.  If you wish to use a product from another company, enter the manufacturer name and the product name.  Manufacturer name:  Product name:  Product name:  Product name:  Product name:  Orive Mechanism Specifications  Orive Mechanism Specifications  Orive Mechanism Specifications  Orive Mechanism  Orive Mechanism	$\square$ $lpha$ step	☐ Stepper Motor	☐ Servo Motor	☐ Electric Actuator	☐ Brushless Motor
Oriental Motor controller  Use positioning function of another company's PLC,  Unknown programmable controller, etc.  If you wish to use a product from another company, enter the manufacturer name and the product name.  Manufacturer name:  Product name:    Drive Mechanism Specifications	☐ AC Motor	☐ Others			
Drive Mechanism Specifications	Desired Controller				
Manufacturer name:  Product name:    Drive Mechanism Specifications	Oriental Mot	or controller Use pos	itioning function of anothermable controller, etc.	er company's PLC, Ou	nknown
Drive Mechanism Specifications  ● If in doubt, leave the applicable fields blank. We will call you if necessary.  Rotating Body Dimensions  ● Writtnal	If you wish to u	se a product from another c	ompany, enter the manufa	acturer name and the produ	ct name.
Rotating Body Dimensions  Width  Vertical:  B = mm  Eccentricity Volume  Postating Body Thickness  C = mm  Rotating Body Mass or Material:  Motor  Position of Mechanism  O Horizontal Plane Rotation  Vertical B  Vertical B  Center of Gravit  Thickness C  Vertical Plane Rotation  Vertical B  O Vertical Plane Rotation  Vertical B  O Vertical Plane Rotation  Width A  Vertical B  Center of Rotation  Vertical B  Center of Rotation  Motor  Center of Gravit  Desired Stopping Accuracy (If any):  Desired Stopping Accuracy (If any):  Power Supply Voltage  V, Hz	Manufacturer	name:	Product na	me:	
Width	■Drive Med	chanism Specifica	tions • If in doubt, leave th	ne applicable fields blank. We will call you	ı if necessary.
Vertical   B	Rotating Body Dim	nensions			
Eccentricity Volume	■ Width ··········		= mm		Rotating Body
Rotating Body Mass or Material  Rotation Rotation  Rotation Speed N  Rotation Speed N  Rotation Angle  Rotation Angle  Rotation Speed N  Rotation Speed N  Rotation Speed N  Rotation Speed N  Rotation Angle []	■ Vertical ········	<u>B</u>	= mm		
Rotating Body Mass or Material	Eccentricity '	Volume······ e	= mm		
Please enter if you use connecting belt pulley or gear. Not required for direct connection.  Primary Side Pulley Diameter and Mass ····· Der = mm   mer = kg   Ler = mm   Materials:  Secondary Side Pulley Diameter and Mass ···· Dee = mm   mer = kg   Ler = mm   Materials:  Secondary Side Pulley Diameter and Mass ···· Dee = mm   mer = kg   Ler = mm   Materials:  Secondary Side Pulley Diameter and Mass ···· Dee = mm   mer = kg   Ler = mm   Materials:  Travel Amount per Rotation Angle ··· Stop Time   Leave the applicable fields blank. We will call you if necessary.  Positioning Time   Leave the applicable fields blank. We will call you if necessary.  Rotation Speed N   Rotation Angle   Time to   Stop Time   Leave the applicable fields blank. We will call you if necessary.  Positioning Time   Leave the applicable fields blank. We will call you if necessary.  Positioning Time   Leave the applicable fields blank. We will call you if necessary.  Positioning Time   Leave the applicable fields blank we will call you if necessary.  Stop Time   Leave the applicable fields blank we will call you if necessary.  Positioning Time to   Stopping Time to	<ul><li>Rotating Boo</li></ul>	dy Thickness ····· C	= mm		
Please enter if you use connecting belt pulley or gear. Not required for direct connection.  Primary Side Pulley Diameter and Mass	<ul><li>Rotating Boo</li></ul>	dy Mass or Material	kg or	material→	Mata
Please enter if you use connecting belt pulley or gear. Not required for direct connection.  Primary Side Pulley Diameter and Mass	Position of M	1echanism			William
Please enter if you use connecting belt pulley or gear. Not required for direct connection.  Primary Side Pulley Diameter and Mass De1 = mm   me1 = kg   Materials:  If the mass is unknown, please enter the width and material. → Le1 = mm   Materials:  Secondary Side Pulley Diameter and Mass De2 = mm   me2 = kg   Materials:  If the mass is unknown, please enter the width and material. → Le2 = mm   Materials:  Poperating Conditions If in doubt, leave the applicable fields blank. We will call you if necessary.  Travel Amount per Rotation Angle  Positioning Time	⊖Horizontal		Width A Vertical B		Center of Rotation  B  Center of Rotation
<ul> <li>Primary Side Pulley Diameter and Mass ······ D<sub>P1</sub> = mm m<sub>P1</sub> = kg</li> <li>If the mass is unknown, please enter the width and material. →</li> <li>Secondary Side Pulley Diameter and Mass ··· D<sub>P2</sub> = mm m<sub>P2</sub> = kg</li> <li>If the mass is unknown, please enter the width and material. →</li> <li>If the mass is unknown, please enter the width and material. →</li> <li>If in doubt, leave the applicable fields blank. We will call you if necessary.</li> <li>Travel Amount per Rotation Angle ···· to = s</li> <li>Desired Acceleration and Deceleration Time· to = s</li> <li>Stop Time···· to = s</li> <li>Desired Travel Rotation Speed (If any) ···· to = s</li> <li>Desired Stopping Accuracy (If any) ··· to = s</li> <li>Power Supply Voltage ···· V, Hz</li> </ul>	○Vertical Pla		Width A Thickness C		C A
● If the mass is unknown, please enter the width and material. →				rect connection.	
Secondary Side Pulley Diameter and Mass. D <sub>P2</sub> = mm m <sub>P2</sub> = kg If the mass is unknown, please enter the width and material. → L <sub>P2</sub> = mm Materials: Operating Conditions If in doubt, leave the applicable fields blank. We will call you if necessary. Travel Amount per Rotation Angle Positioning Time Desired Acceleration and Deceleration Time. Stop Time Stop Time Desired Travel Rotation Speed (If any) N = to r/min Desired Stopping Accuracy (If any) Power Supply Voltage V, Hz	Primary Side Pu	ulley Diameter and Mass ······ D	P1 = mm	$m_{P1} = k$	<u>g</u>
Operating Conditions If in doubt, leave the applicable fields blank. We will call you if necessary. Travel Amount per Rotation Angle Positioning Time	If the ma	ass is unknown, please ente	r the width and material.	$\rightarrow$ $L_{P1}$ = n	nm Materials:
Operating Conditions ● If in doubt, leave the applicable fields blank. We will call you if necessary.  Orange Amount per Rotation Angle ····  Operating Time ····  Operating Conditions • If in doubt, leave the applicable fields blank. We will call you if necessary.  Rotation Speed N Operating Conditions • If in doubt, leave the applicable fields blank. We will call you if necessary.  Rotation Speed N Operating Conditions • If in doubt, leave the applicable fields blank. We will call you if necessary.  Rotation Angle [*]  Rotation Angle [*]  Acceleration Deceleration	Secondary Side	Pulley Diameter and Mass… D	P2 = mm	$m_{P2} = k$	<u>g</u>
Travel Amount per Rotation Angle or Positioning Time to s  Desired Acceleration and Deceleration Time to s  Stop Time to s  Desired Travel Rotation Speed (If any) or to some the second of the second or to some the second	If the ma	ass is unknown, please ente	r the width and material.	$\rightarrow$ $L_{P2}$ = n	nm Materials:
Positioning Time  to = s  Desired Acceleration and Deceleration Time  t <sub>1</sub> = s  Stop Time  Desired Travel Rotation Speed (If any)  Desired Stopping Accuracy (If any)  Power Supply Voltage  V, Hz	<b>■</b> Operating	Conditions If in dou	ubt, leave the applicable fields blank. W	e will call you if necessary.	
Desired Acceleration and Deceleration Time:  Stop Time	■Travel Amou	nt per Rotation Angle·····	•	Rotation Speed N	
Desired Acceleration and Deceleration Time:    tr = s	<ul><li>Positioning T</li></ul>	Time to	= s	Ī / [	
Desired Travel Rotation Speed (If any)	<ul><li>Desired Acceler</li></ul>	ration and Deceleration Time $t_1$	= s	]  /   [	Rotation Angle [*]
<ul> <li>Desired Travel Rotation Speed (If any) ········· N = to r/min</li> <li>Desired Stopping Accuracy (If any) ··· ±</li> <li>Power Supply Voltage ······· V, Hz</li> </ul>	● Stop Time ···		= s	Ī <u>/ </u>	
Desired Stopping Accuracy (If any)   Positioning Time to [S] Stopping Time to [S]  Positioning Time to [S] Stopping Time to [S]	Desired Travel I	Rotation Speed (If any)	= to	* ° 171,	me t1 Time t1
Power Supply Voltage		_			sitioning Time to [S] Stopping Time t <sub>2</sub> [S]
				<u> </u>	
				○ No	

thers			
ication, Equipment Name		(c) \(\frac{1}{2} \)	
nated Number of Units to be Used ·····		unit(s)	
nated Purchase Date ·····	year	month	
oly Source (Sales office)	itten about ata\		
er (Requests, Contact information, Items not wr			