## **Product Recommendation Information Sheet**

## **Rotating Body/Index Table**

Desired Pi	I Oduct I f you have n	o desired product, leave t	he applicable fields	blank. We will call you if necessar	у.	
Desired Motor(s)						
$\square$ $lpha$ step	☐ Stepper Motor	☐ Servo N	Motor	☐ Electric Actuator	☐ Brushless Moto	or
☐ AC Motor	Others					
Desired Controller						
Oriental Moto	or controller Use	positioning functions	tion of anothe	er company's PLC,	○ Unknown	
If you wish to us	se a product from anot	her company, ent	er the manufa	acturer name and the p	roduct name.	
Manufacturer	name:		Product na	me:		
■Drive Mec	hanism Specif	ications •	Miles devoka Jessey all	on and the black of the selection of the		
-		ications	or in doubt, leave tr	ne applicable fields blank. We will o		ia ration
Table Shape and Di		10 -	mm	7	Drive Mechanism Conf	iguration .
O DISK Diamei	ter ·····	·   φD =	mm	_	Load	Table
○ Square Vert	ical Length	· [A =	mm		Shaft	Secondary Side Pulley
Wid	th Length ·····	··   B =	mm		Connecting Belt	Primary Side Pulley
■ Table Thickne	ess	· [t =	mm			Motor
■ Table Mass of	r Material ·····	· <u>m</u> =	kg or	material→ ¬		
_	iameter		mm		Table Shape	→ B
■ Table Shaft Le	ength ·····	· L =	mm		♦D t	
_	lass or Material		kg or	material→		A
_	ne Load and Dimensior			٦	Load Shape	
O Cylinder Dia	ameter ·····	$\Phi D_W =$	mm			
<ul><li>Quadrangula</li></ul>	r Prism Vertical lengt	h Aw =	mm		hw	hw
	Width length	[Bw =	mm		1	Bw
■Load Height··		· hw =	mm		ΦDw	Aw
<ul><li>Load Mass or</li></ul>	r Material·····	· [mw =	kg or	material→		an a rain
<ul><li>Load Rotation</li></ul>	n Radius······	· [r =	mm			
<ul><li>Number of Lo</li></ul>	oads	· n =	unit(s)			
<ul><li>Inclination An</li></ul>	gle of the Mechanism	· \[ \theta \] =	deg.	Pe	osition of Mechanism	θ
Please enter if you	consider frictional load	. Not required if fr	rictional load i	s negligible.		
Friction Coefficie	ent for Rotating Body and S	upport Component ···	··· μ =		<b>←→</b>	→   ←
If this is ur	nknown, enter the materials	for the support com	ponents $\rightarrow$ N	laterials:		
Distance From R	Rotation Center to Support C	omponents*	· / =	mm		o b
(*Support cor	mponent refers to bear	ings, etc. For bea	ırings, enter tl	ne outer diameter.)		μ
Please enter if you	use connecting belt pu	lley or gear. Not r	equired for di	rect connection.		
Primary Side Pul	lley Diameter and Mass ·····	D <sub>P1</sub> =	mm	<i>m</i> <sub>P1</sub> =	kg	
If the ma	ass is unknown, please	enter the width a	nd material.	<i>L</i> <sub>P1</sub> =	mm Materials:	
Secondary Side	Pulley Diameter and Mass	··   D <sub>P2</sub> =	mm	m <sub>P2</sub> =	kg	
If the ma	ss is unknown, please	enter the width a	nd material	→ L <sub>P2</sub> =	mm Materials:	
<b>■</b> Operating	Conditions •	f in doubt, leave the appli	cable fields blank. V	le will call you if necessary.		
Travel Amount p	er Rotation Angle·····		٥	Rotation Speed N		
Positioning Time	······	·· [to =	S		Potation Angle [*]	
Desired Accelera	ation and Deceleration Time	· t1 =	S	]  /	/ Rotation Angle [1]	
Stop Time		$\cdot \cdot \boxed{t_2} =$	S	]	Acceleration Deceleration	
Desired Travel R	otation Speed (If any) ·······	·· N =	to	r/min	Time t1 Time t1	
	g Accuracy (If any) ······		•	<b>─</b>	Positioning Time to [S]	Stopping Time t <sub>2</sub> [S]
	oltage		V,	Hz		
	ding Force After Power is Tu		○ Yes	○ No		
INCOCOSILY OF HOL	ung rolde Alter FUWER IS IL	iiiidu vii	<u> </u>	U INU		

thers			
ication, Equipment Name		(c) \(\frac{1}{2} \)	
nated Number of Units to be Used ·····		unit(s)	
nated Purchase Date ·····	year	month	
oly Source (Sales office)	itten about ata\		
er (Requests, Contact information, Items not wr			